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FORMAMOS LÍDERES
RESPONSABLES
PARA EL MUNDO_

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Distribution of non-alcoholic beverages in the city of Lima

AGENDA

Introduction

Methodology

Results

Conclusions

References



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Introduction

The purpose



The purpose of this paper is to analyze the transportation configuration characteristics of non-alcoholic beverages in a Latin-American city

The city

Which are the more congested cities in the world?

Ranking of the most congested cities Globally (Overall daily congestion level – extra travel time – population over 800,000):

1	Mumbai, India	65%	6	Istanbul, Turkey	53%
2	Bogota, Colombia	63%	7	Jakarta, Indonesia	53%
3	Lima, Peru	58%	8	Bangkok, Thailand	53%
4	New Delhi, India	58%	9	Mexico City, Mexico	52%
5	Moscow, Russia	56%	10	Recife, Brazil	49%

The city



The model

The model proposes routes that improve customer satisfaction due to on-time deliveries through the administration of inventories and the paths of the trucks filling pending orders

The constraints



- Limited number of trucks that also have a limited capacity
- Loading requirements that are established in the contracts
- Inventory limitations
- Product stacking limitations



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Methodology

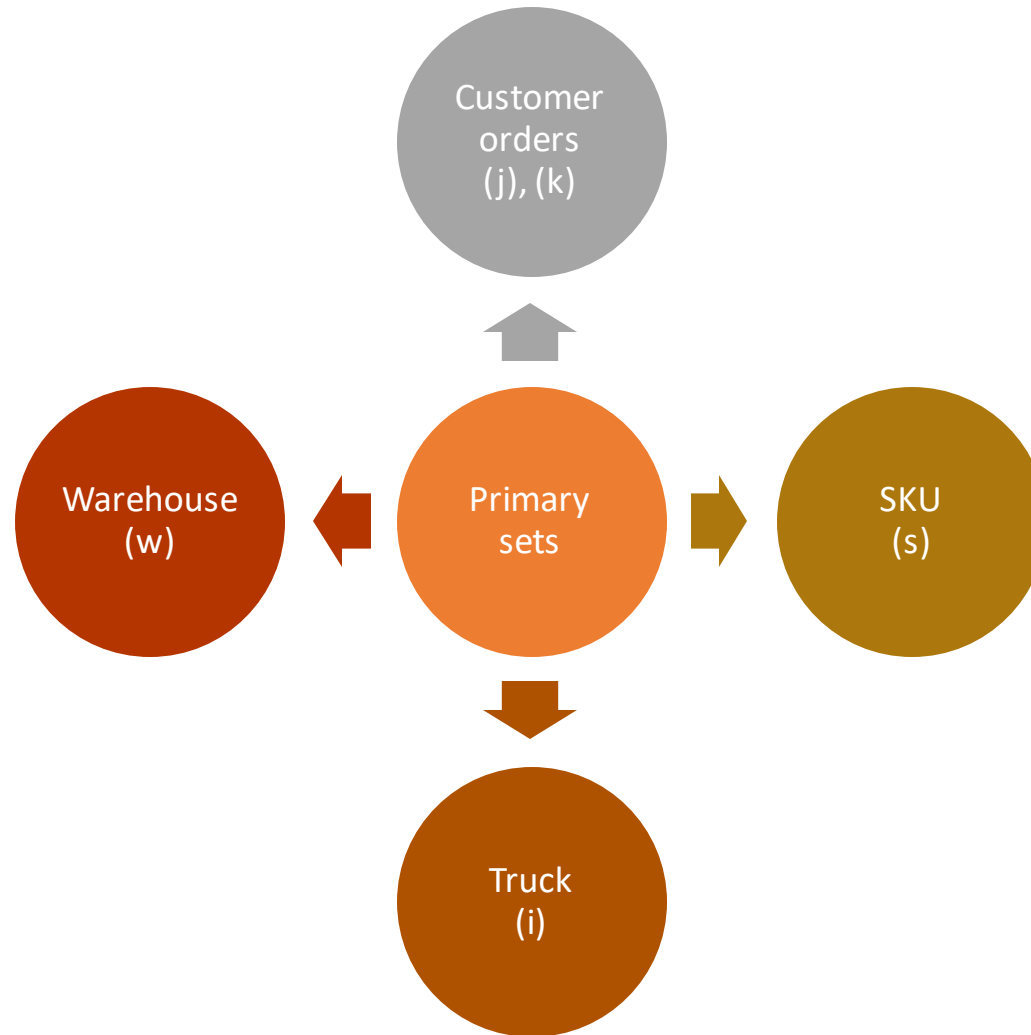
The model

A goal programming model is proposed to schedule the transportation of non-alcoholic beverages from the distribution centers to the points of sale through fleets of trucks with different characteristics

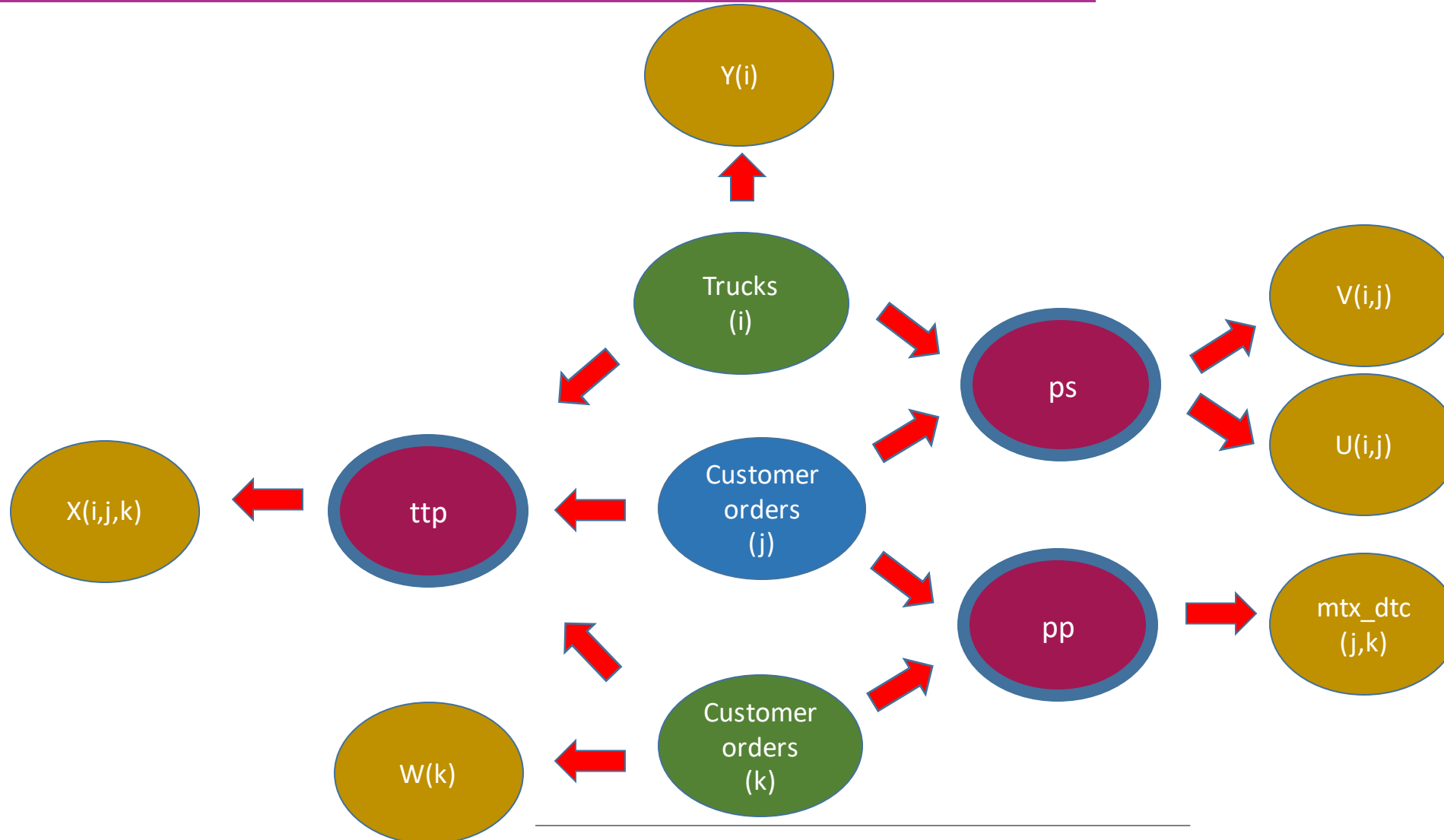
The goals

The goals include the fulfillment of the number of pending orders, the number of available trucks, the contractually bound capacity and the distance that trucks will travel to fill the orders

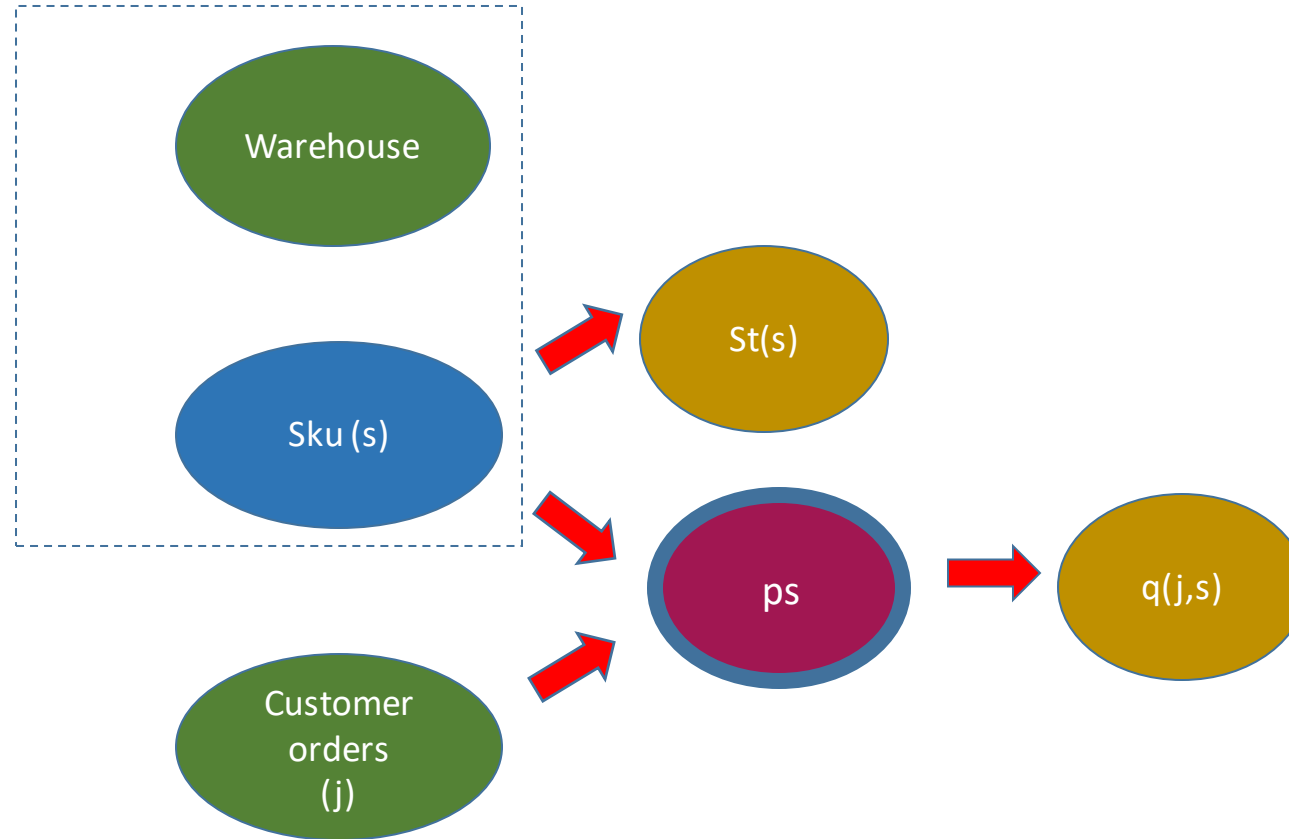
Primary sets



Secondary sets



Secondary sets

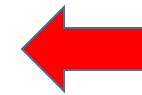


The objective

Goals

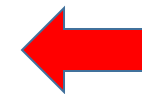
$$\text{Min } z = \text{not_attended} + \frac{\text{etrucks}}{\text{MinTrucks}} + \sum_{i=1}^m e2cap_i + \frac{\text{edst}}{\text{Max_Dst}}$$

$$\sum_{j=1}^n \frac{W_j}{n} + \text{not_attended} = 1$$



Fullfilment

$$\sum_{i=1}^m Y_i + \text{dtrucks} - \text{etrucks} = \text{MinTrucks}$$

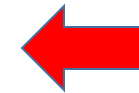


Number of trucks

The objective

Goals

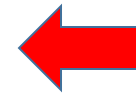
$$\sum_{i=1}^m weight_i * V_{ij} + d1cap_i - e1cap_i = capacity_i * Y_i \forall i \in trucks$$



Truck capacity

$$\sum_{i=1}^m \frac{d1cap_i}{LIM_CAP * capacity_i} + d2cap_i - e2cap_i = Y_i \forall i \in trucks$$

$$\sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^n / j \neq k mtxdst_k * X_{ijk} + ddst - edst = Max_Dst$$



Distance

The constraints

$$\sum_{k=1}^n X_{i0k} = Y_i \forall i \in trucks$$

$$\sum_{k=1}^n X_{ik(n+1)} = Y_i \forall i \in trucks$$

$$\sum_{k=1}^n X_{i(n+1)k} = 0 \forall i \in trucks$$

$$X_{i0(n+1)} = 0 \forall i \in trucks$$

Trucks constraints: start point, routes, points

The constraints

$$\sum_{k=1}^n \sum_{i=1}^m X_{ijk} \leq 1 \quad \forall j \in \text{point_of_distribution} \setminus \{0, n + 1\}$$

$$\sum_{j=1}^n \sum_{i=1}^m X_{ijk} \leq 1 \quad \forall k \in \text{point_of_distribution} \setminus \{0, n + 1\}$$

Route constraints - points

$$\sum_{j=1/j \neq k}^n X_{ijk} = \sum_{j=1/j \neq k}^n X_{ikj} \quad \forall i \in \text{trucks}, k \in \text{point_of_distribution} \setminus \{0, n + 1\}$$

The constraints

$$U_{ik} \leq U_{ij} + 1 - (n + 2)(X_{ijk} - 1) \quad \forall i \in \text{trucks}, (j,k) \in \text{point_of_distribution} \times \text{point_of_distribution} / j \neq k$$

$$U_{ik} \geq U_{ij} + 1 + (n + 2)(X_{ijk} - 1) \quad \forall i \in \text{trucks}, (j,k) \in \text{point_of_distribution} \times \text{point_of_distribution} / j \neq k$$

$$\sum_{j=1}^n \text{weight}_j V_{ij} \leq \text{capacity}_i Y_i \quad \forall i \in \text{trucks}$$

Balance constraints

The constraints

$$\sum_{j=1}^n q_{js} W_j \leq st_s \quad \forall s \in sku$$

Inventory constraints

$$W_k = \sum_{i=1}^m \sum_{j=1}^n X_{ijk} \quad \forall k \in point_of_distribution \setminus \{0, n + 1\}$$



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Process

The input was the structure of the trucks, orders, products and coordinates of the point of sales in a Latin American city

Table 1

Types of container used in the SKU of the simulated orders

Container	Quantity SKU	Percentage SKU
Packaging board	7	15.9%
Glass	10	22.7%
PET	23	52.3%
Metal	4	9.1%
Total	44	100.0%

Source: author's own elaboration.

Process

Autoguardado Ruta R1 4 vehiculos x 60 pedidos Bodegas Lima V0.xl... Buscar Juan Machuca JM

Archivo Inicio Insertar Disposición de página Fórmulas **Datos** Revisar Vista Programador Ayuda Power Pivot PrecisionTree Diseño de tabla Compartir Comentarios

Obtener y transformar... Actualizar todo... Cotizaciones Geografía Ordenar Filtro Borrar Volver a aplicar Avanzadas Herramientas de datos Previsión Esquema Solver Solve Model Show Model Edit Data Show/Hide Data Show Data in Color SolverStudio

E3 0

	A	B	C	D	E	F
1						
2	Punto	Descripción	Peso pedido	Cajas No Enc	Atendido	COORDX
3	P1		0	0		301874.9
4	P1638		569.23	18		290936.9
5	P1639		188.3	7		294433.1
6	P1655		46.6	3		292738.2
7	P1658		66.3	4		290408.9
8	P1659		104.8	5		290067.3
9	P1660		4.1	0		290564.3
10	P1661		15	2		290777.3
11	P1662		125.8	8		291094.4
12	P1663		154.3	8		291538.8
13	P1664		77.5	3		296415.3
14	P1665		23.2	0		285327.8
15	P1667		81.7	3		294124.4
16	P1668		29.3	2		290373.6
17	P1669		128.1	3		301851.
18	P1670		120.93	3		284370.2
19	P1671		73.2	3		290697.4

SolverStudio © Andrew Mason

File Edit Language Gurobi

```

from gurobipy import *
from SolverStudio import *

m = Model("Camiones")

## Define variables
X={}
for c in CAMION:
    for d in DESTINO:
        for e in DESTINO:
            if d!=e:
                X[c,d,e] = m.addVar(vtype=GRB.BINARY, name='X %s %s %s %s' % (c,d,e))

```

Model Output

```

## Executing C:\Users\Juan\Downloads\SolverStudio_00_09_03_00
20160520\SolverStudio_00_09_03_00 20160520\SolverStudio\SolverStudio\GurobiPython
\RunGurobiPython.py
## Building Gurobi input file, module 'SolverStudio.py', for 16 data items
## Writing data items
Academic license - for non-commercial use only
Changed value of parameter MIPGap to 0.05

```

Row 188, Column 15

```
NOATENDIDOS= m.addVar(obj=1000, name='NOATENDIDOS')
```

```
ECAMIONES= m.addVar(obj=1, name='ECAMIONES')
```

```
EDST= m.addVar(obj=1, name='EDST')
```

```
m.update()
```

```
m.setObjective(ECAMIONES+NOATENDIDOS*1000+ EDST+ quicksum(D2CAP[i] for i in CAMION) );
```

```
m.modelSense = GRB.MINIMIZE
```

```
#familia 1
```

```
for i in CAMION:
```

```
    m.addConstr(quicksum(X[i,DESTINO[0],k] for k in DESTINO
```

```
        if DESTINO.index(k)!=0 and DESTINO.index(k)!=len(DESTINO)-1)==Y[i]);
```

```
for i in CAMION:
```

```
    m.addConstr(quicksum(X[i,k,DESTINO[len(DESTINO)-1]] for k in DESTINO
```

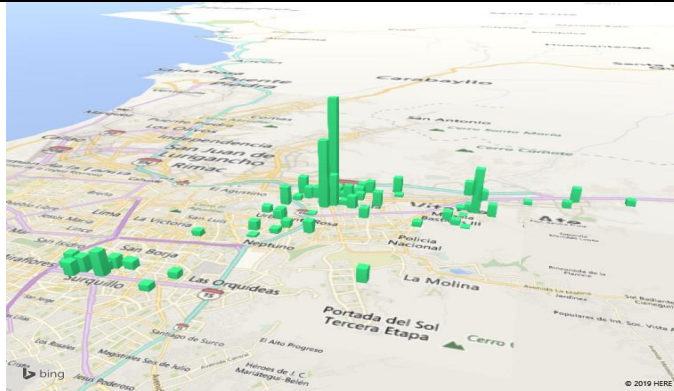
```
        if 0!=DESTINO.index(k) and len(DESTINO)-1!=DESTINO.index(k))==Y[i]);
```



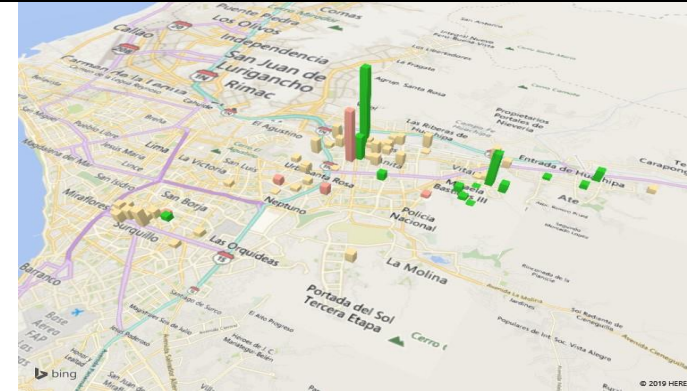
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Results

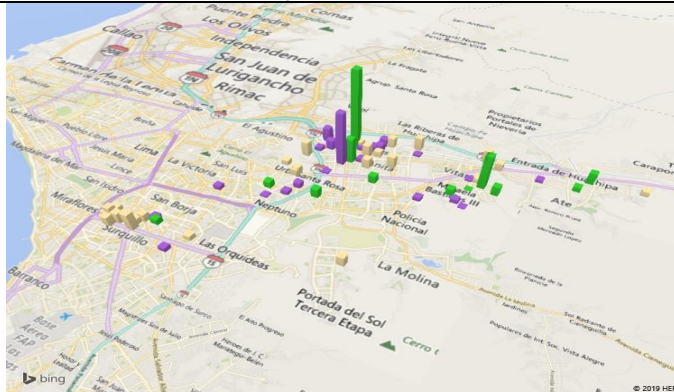
Results – Order point of sales



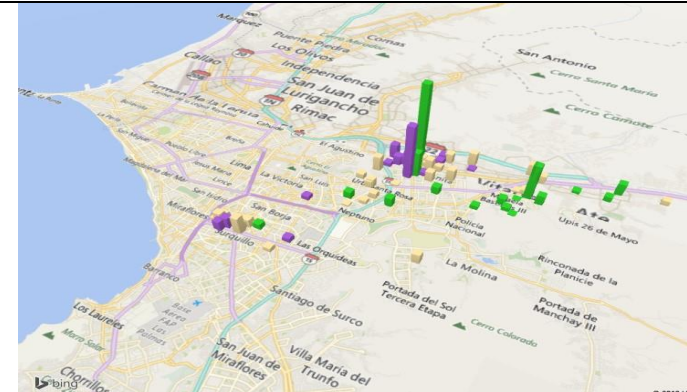
Points of delivery



Route with 20% GAP



Routes with 10% GAP



Routes with 5% GAP

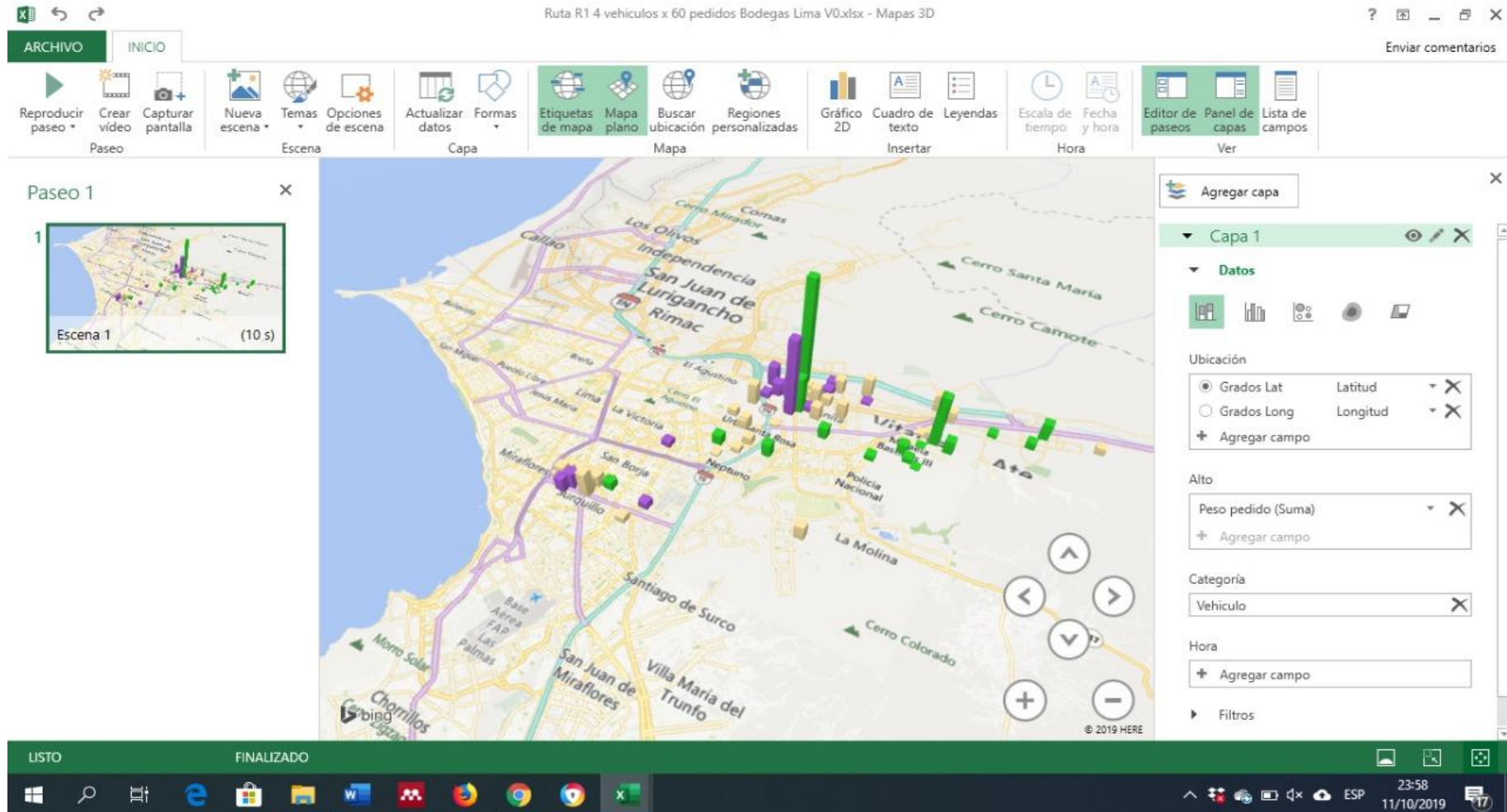


Table 2

The meeting of goals with sufficient inventory

Points of delivery	Vehicles assigned	% of orders filled	% of capacity used	Route Distance (km)
10	1	100	23	15.9
20	1	100	56	23.6
30	1	100	50	24.6
40	1	100	66	26.6
50	1	100	88	29.4
60	2	100	78	33.2
70	2	100	79	36.6

Source: author's own elaboration.

Results

The solutions allowed the scheduling of orders that had specific transportation units assigned with a graphical route

Results



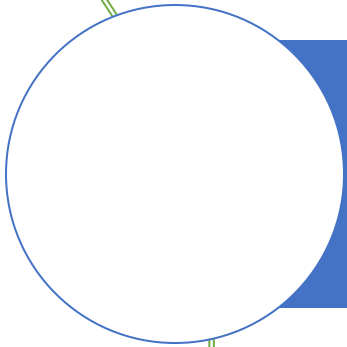
The percentage of filled order will improve the decision making process when the time for a route design is limited



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Conclusions

Conclusions



We propose a model to design the shortest routes that can be used in an heterogeneous fleet with known capacities

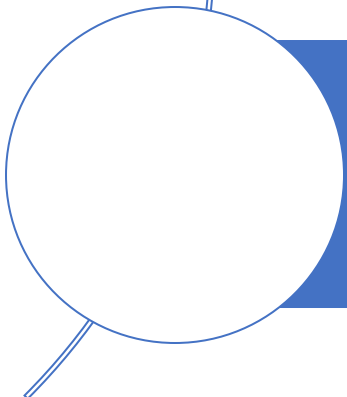


The results show that it is possible to find a solution when the process time depends on the number of delivery points

Conclusions



One of the main contributions of the goal programming model proposal is that allows to manage the priorities in a distribution planning



As future research, we propose other constraints such as route options, time windows, among others

Conclusions

Managerial implications

The points of distribution can be supplied by located warehouses

The results facilitate coordination within the stakeholders



Research implications

The model combines multiple operational goals

We can optimize considering the preventive and response stage



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